

General Description

TD2596HV is a monolithic asynchronous buck regulator. The device provides 2.5A of continuous load current over a wide input voltage of 4.5V to 60V. It uses current mode control to regulator the output voltage and provides fast transient response.

Requiring a minimum number of external components, these regulators are simple to use and include internal frequency compensation, and a fixed-frequency oscillator.

This device, available in a TO263-5 package, provides a very compact system solution with minimal reliance on external components.

Features

- Internal Power MOSFET
- 2.5A continuous output current
- Up to 90% efficiency
- Input voltage range: 4.5V to 60V
- Fixed 150kHz frequency internal oscillator
- Current limit protection
- Over temperature protection
- TO263-5 package

Applications

- Simple high-efficiency step-down regulator
- Efficient pre-regulator for linear regulators
- On-card switching regulators
- Positive to negative converter
- Battery charger

Pin Configurations

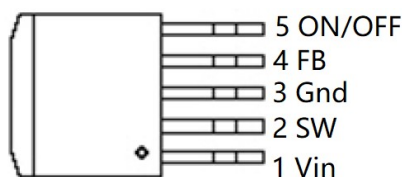


Figure1 Pin Configuration of TD2596HV(Top View)

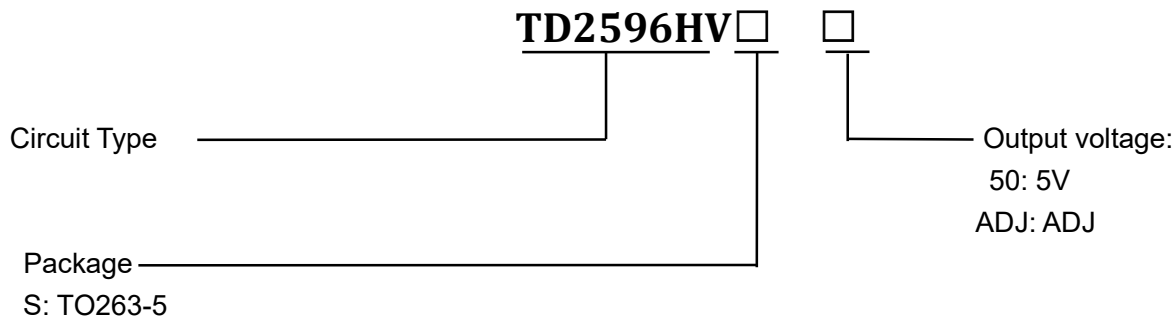
150KHz 60V 2.5A Buck DC/DC Converter

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Pin Description

Pin Number	Pin Name	Description
1	VIN	Power Input. In supplies the power to the IC, as well as the step-down converter switches. Drive IN with a 4.5V to 60V power source. Bypass IN to GND with a suitably large capacitor to eliminate noise on the input to the IC. See Input Capacitor.
2	SW	Power Switching Output. SW is the switching node that supplies power to the output. Connect the output LC filter from SW to the output load.
3	GND	Ground.
4	FB	Feedback Input. FB senses the output voltage to regulate that voltage. Drive FB with a resistive voltage divider from the output voltage. The feedback threshold is 1.23V.
5	ON/OFF	Enable Input. ON/OFF is a digital input that turns the regulator on or off. Diver ON/OFF low to turn on the regulator

Ordering Information



Function Block

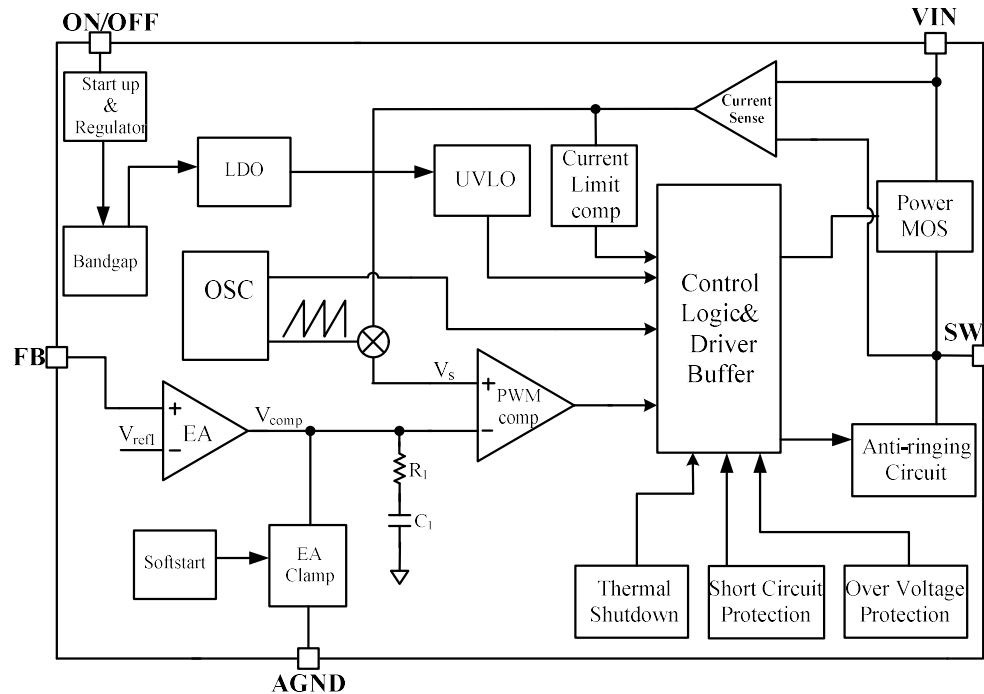


Figure 2 Function Block Diagram of TD2596HV

Absolute Maximum Ratings

Parameter	symbol	Value	Unit
Input Voltage	V_{IN}	-0.3 to 63	V
Feedback Pin Voltage	V_{FB}	-0.3 to 5	V
ON/OFF Pin Voltage	V_{EN}	-0.3 to 5	V
Output Pin Voltage	V_{SW}	-0.3 to $V_{IN}+0.3$	V
Power Dissipation	P_D	Internally limited	mW
Operating Junction Temperature	T_J	150	°C
Storage Temperature	T_{STG}	-65 to 150	°C
Lead Temperature	T_{LEAD}	260	°C
MSL		Level3	
Thermal Resistance-Junction to Ambient	$R_{\theta JA}$	50	°C/W
Thermal Resistance-Junction to Case	$R_{\theta JC}$	10	°C/W

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Recommended Operating Conditions

Parameter	Symbol	Min.	Max.	Unit
Input voltage	V_{IN}	4.5	60	V
Output voltage	V_{out}	1.23		V
Converter output current	I_{out}	0	2.5	A
Operating junction temperature	T_J	-40	125	°C
Operating ambient temperature	T_A	-40	85	°C

Electrical Characteristics

VIN =12V, TA =+25°C, unless otherwise noted

Parameter	Symbol	Condition	Min	Typ	Max	Units
TD2596HVSADJ	V_{FB}	$4.5V \leq V_{IN} \leq 60V$	1.193	1.23	1.267	V
TD2596HVS50	V_{OUT}		4.8	5.0	5.2	V
Shutdown Supply Current		ON/OFF=5V	-	-	10	uA
Quiescent current	I_Q	ON/OFF=0V; $V_{FB}=1.5V$	-	3	4.5	mA
Oscillation Frequency	F_{OSC1}	$V_{FB} > 0.3$	120	150	180	kHz
Highside Switch On Resistance	$R_{DS(ON)}$		-	500	-	mΩ
Current Limit	I_L	Peak output current	-	3.2	-	A
Maximum Duty Cycle	D_{MAX}		-	-	100	%
ON/OFF Threshold voltage	V_{IL}	Low(Regulator ON)	-	0.9	-	V
	V_{IH}	High(Regulator OFF)	-	1.0	-	V
Input Under Voltage Lockout Threshold		V_{IN} Rising	-	4.0	-	V
Input Under Voltage Lockout Threshold Hysteresis			-	300	-	mV
Thermal Shutdown			-	150	-	°C
Thermal Hysteresis			-	40	-	°C

Typical Application Circuit

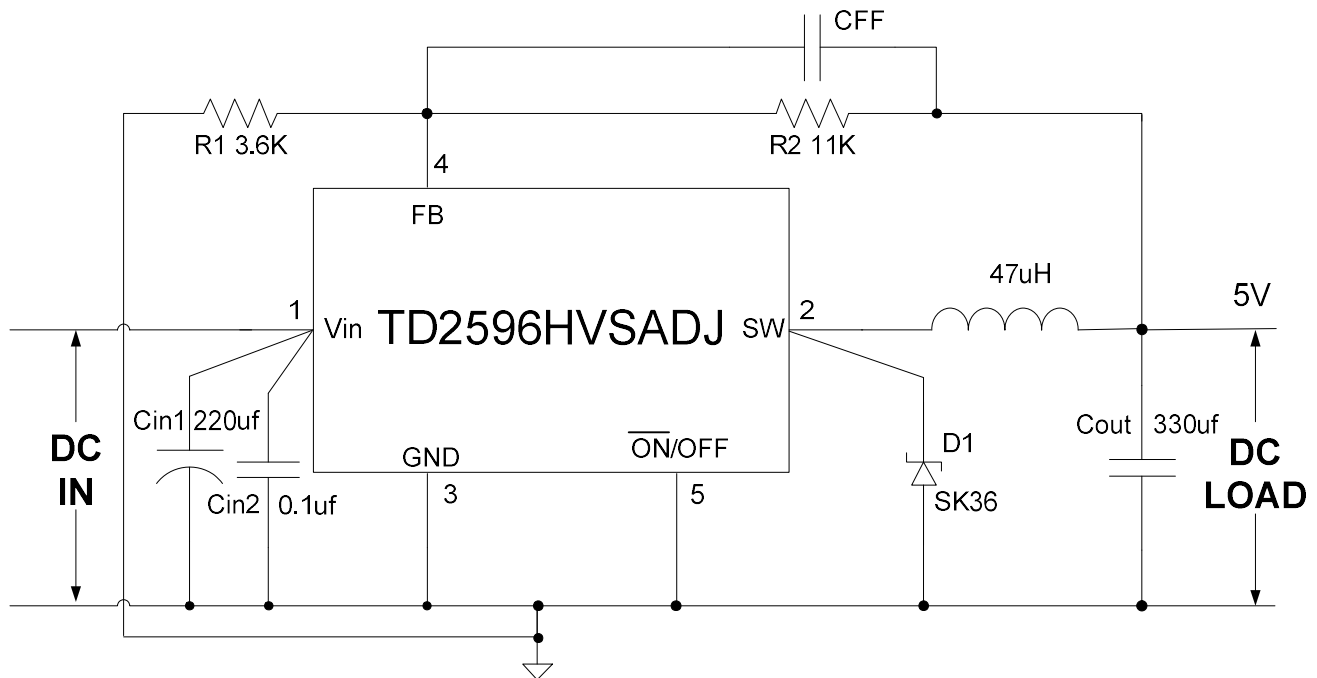


Figure 3 Typical Application of TD2596HVSADJ

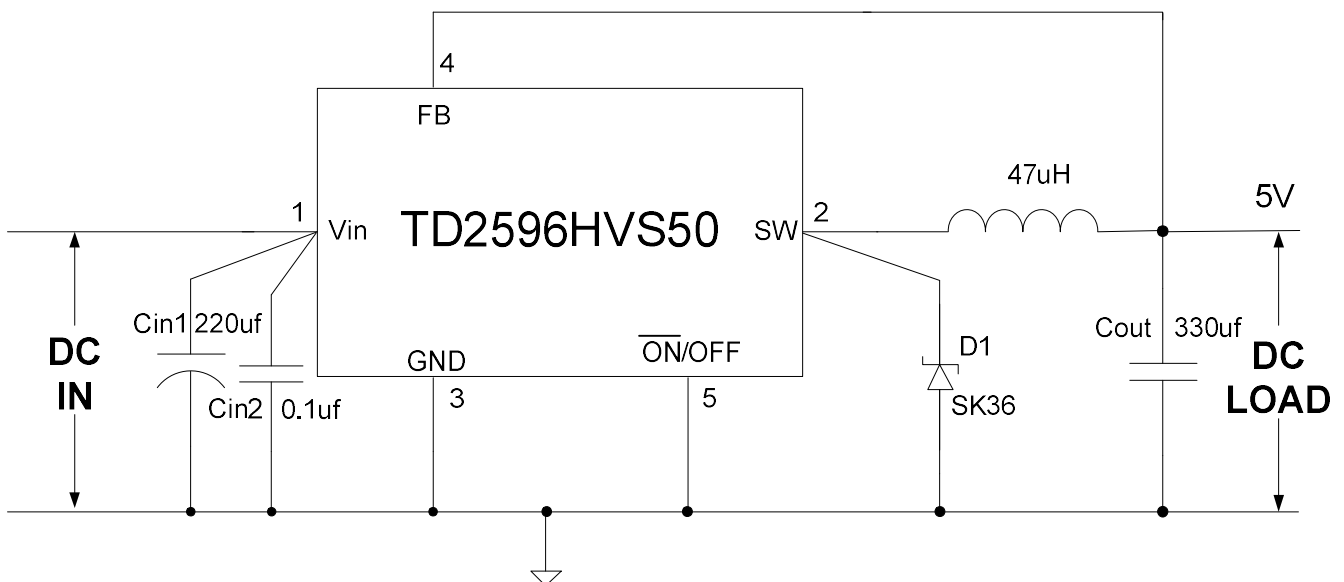


Figure 4 Typical Application of TD2596HVS50

Function Description

The TD2596HV regulates input voltages from 4.5V to 60V down to an output voltage as low as 1.23V, and supplies up to 2.5A of load current.

The TD2596HV uses current-mode control to regulate the output voltage. The output voltage is measured at FB through a resistive voltage divider and amplified through the internal trans-conductance error amplifier. The output voltage of the error amplifier is compared to the switch current (measured internally) to control the output voltage.

Setting the Output Voltage

The output voltage is set using a resistive voltage divider connected from the output voltage to FB. The voltage divider divides the output voltage down to the feedback voltage by the ratio:

$$V_{FB} = V_{OUT} \times \left(\frac{R_1}{R_1 + R_2} \right)$$

Thus the output voltage is:

$$V_{OUT} = 1.23 \times \left(\frac{R_1 + R_2}{R_1} \right)$$

Inductor

The inductor is required to supply constant current to the load while being driven by the switched input voltage. A larger value inductor will result in less ripple current that will in turn result in lower output ripple voltage. However, the larger value inductor will have a larger physical size, higher series resistance, and/or lower saturation current. A good rule for determining inductance is to allow the peak-to-peak ripple current to be approximately 30% or the maximum switch current limit. Also, make sure that the peak inductor current is below the maximum switch current limit.

The inductance value can be calculated by:

$$L = \frac{V_{OUT}}{f_s \times \Delta I_L} \times \left(1 - \frac{V_{OUT}}{V_{IN}} \right)$$

Where V_{OUT} is the output voltage, V_{IN} is the input voltage, f_s is the switching frequency, and ΔI_L is the peak-to-peak inductor ripple current.

Choose an inductor that will not saturate under the maximum

inductor peak current, calculated by:

$$L_P = I_{LOAD} + \frac{V_{OUT}}{2 \times f_s \times L} \times \left(1 - \frac{V_{OUT}}{V_{IN}} \right)$$

where I_{LOAD} is the load current.

The choice of which style inductor to use mainly depends on the price vs. size requirements and any EMI constraints.

Input Capacitor

The input current to the step-down converter is discontinuous, therefore a capacitor is required to supply the AC current while maintaining the DC input voltage. Use low ESR capacitors for the best performance. Ceramic capacitors are preferred, but tantalum or low-ESR electrolytic capacitors will also suffice. Choose X5R or X7R dielectrics when using ceramic capacitors. Since the input capacitor (C_{in1}) absorbs the input switching current, it requires an adequate ripple current rating. The RMS current in the input capacitor can be estimated by:

$$I_{Cin1} = I_{LOAD} \times \sqrt{\frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}} \right)}$$

The worst-case condition occurs at $V_{IN}=2V_{OUT}$, where $I_{Cin1} = I_{LOAD}/2$. For simplification, use an input capacitor with a RMS current rating greater than half of the maximum load current. The input capacitor can be electrolytic, tantalum or ceramic. When using electrolytic or tantalum capacitor, be placed as close to the IC as possible. When using ceramic capacitors, make sure that they have enough capacitance to provide sufficient charge to prevent excessive voltage ripple at input. The input voltage ripple for low ESR capacitors can be estimated by:

$$\Delta V_{IN} = \frac{I_{LOAD}}{C_1 \times f_s} \times \frac{V_{OUT}}{V_{IN}} \left(1 - \frac{V_{OUT}}{V_{IN}} \right)$$

where C_{in1} is the input capacitance Value.

Output Capacitor

The output capacitor (C_{out}) is required to maintain the DC output voltage. Ceramic, tantalum, or low ESR electrolytic capacitors are recommended. Under typical application

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conditions, a minimum ceramic capacitor value of 20μF is recommended on the output. Low ESR capacitors are preferred to keep the output voltage ripple low. The output voltage ripple can be estimated by:

$$\Delta V_{OUT} = \frac{V_{out}}{f_s \times L} \times \left(1 - \frac{V_{out}}{V_{in}}\right) \times \left(R_{ESR} + \frac{1}{8 \times f_s \times C_{out}}\right)$$

Where Cout is the output capacitance value and RESR is the equivalent series resistance (ESR) value of the output capacitor.

When using ceramic capacitors, the impedance at the switching frequency is dominated by the capacitance which is the main cause for the output voltage ripple. For simplification, the output voltage ripple can be estimated by:

$$\Delta V_{OUT} = \frac{V_{OUT}}{8 \times f_s^2 \times L \times C_{out}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

When using tantalum or electrolytic capacitors. The ESR dominates the impedance at the switching frequency. For simplification, the output ripple can be approximated to:

$$\Delta V_{OUT} = \frac{V_{OUT}}{f_s \times L} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \times R_{ESR}$$

The characteristics of the output capacitor also affect the stability of the regulation system. The TD2596HV can be optimized for a wide range of capacitance and ESR values.

negative pole is as short and thick as possible to the inductor and chip PIN2.

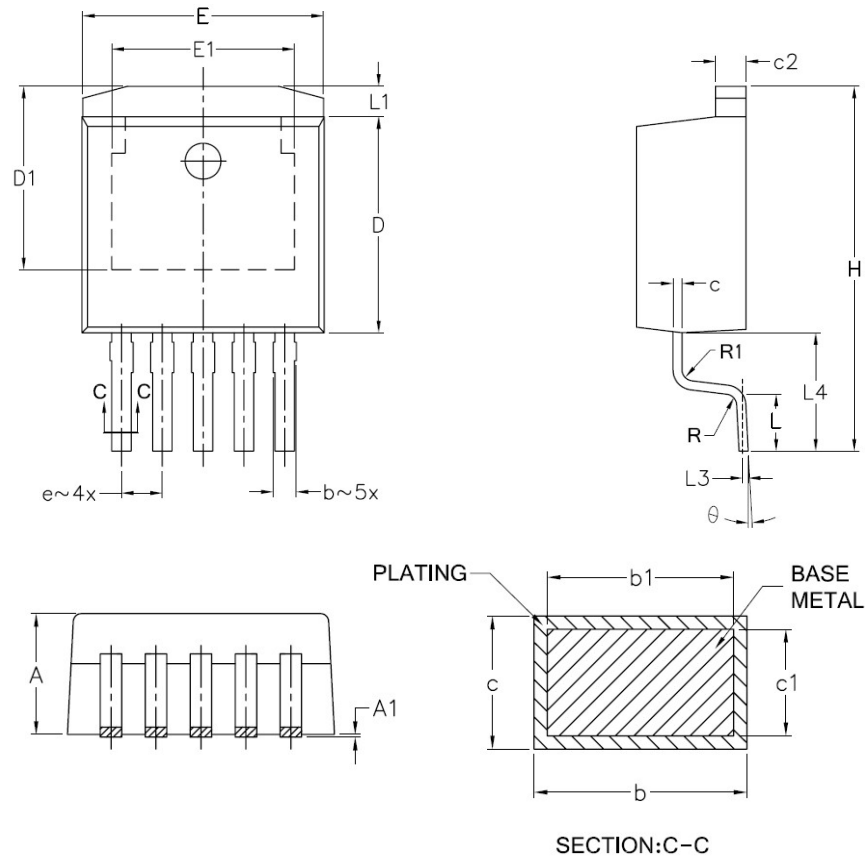
PCB Layout Guide

Follow the following guidelines for PCB design to get the best performance from TD2596HV

1. The input and output power loop area is minimized (the thick line part in the figure), and the EMC test is easier to meet the standard.
2. Input capacitors CIN1 and CIN2 are as close as possible to chip PIN1 to help absorb transient peak voltage and reduce input ripple.
3. The feedback voltage divider R1 and R2 are close to the chip pin end, and the feedback Voltage is sampled from the positive extreme of the output filter capacitor, and the line is far away from the inductor and diode, so as to cover the ground as much as possible to ensure high sampling accuracy and more stable output voltage.
4. There is switching noise on both positive and negative poles of D1. To reduce interference, ensure that the positive pole of D1 is directly connected to the chip GND, and the

Package Information

T0263-5L Package Outline Dimensions



SYMBOLS	COMMON			
	MM		INCH	
	MIN.	MAX.	MIN.	MAX.
A	4.064	4.826	0.160	0.190
A1	0.000	0.254	0.000	0.010
b	0.508	0.991	0.020	0.039
b1	0.508	0.889	0.020	0.035
c	0.381	0.737	0.015	0.029
c1	0.381	0.584	0.015	0.023
c2	1.143	1.651	0.045	0.065
D	8.382	9.652	0.330	0.380
D1	6.858	7.700	0.270	0.303
E	9.652	10.668	0.380	0.420
E1	6.223	8.000	0.245	0.315
e	1.702	BSC.	0.067	BSC.
H	14.605	15.875	0.575	0.625
L	1.778	2.794	0.070	0.110
L1	1.000	1.676	0.039	0.066
L3	0.254	BSC	0.010	BSC
L4	4.780	5.280	0.188	0.208
R	0.460	TYP	0.018	TYP
R1	0.460	TYP	0.018	TYP
θ	0°	8°	0°	8°

Design Notes